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Vector Mechanics for Engineers: Statics Edition. 2 - 15. Rectangular Components of a Force: Unit Vectors  
Vector components may be expressed as products of the unit vectors with the scalar magnitudes of the vector components.  $F_x$  and  $F_y$  are referred to as the scalar components of  $F$ .  $F = F_x i + F_y j$  May resolve a force vector ...

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Eighth Vector Mechanics for Engineers: Statics Edition 3 - 1 How to prepare for the midterm  $\hat{c}$  The midterm will be based on Chapters 1-5 and sections 6.1-6.7. It will be one-hour, take-home, open-text book and open-notes exam. ... resultant force vector and a resultant couple vector,

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Seventh Vector Mechanics for Engineers: Dynamics Edition 16 - 7 Axioms of the Mechanics of Rigid Bodies  $\hat{c}$  The forces act at different points on a rigid body but but have the same magnitude, direction, and line of action.  $F F r r$  and  $\hat{c}^2 \hat{c}$  The forces produce the same moment about any point and are therefore, equipollent external forces.

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Seventh Vector Mechanics for Engineers: Dynamics Edition 15 - 5 Rotation About a Fixed Axis. Velocity  $\hat{v}$   
Consider rotation of rigid body about a fixed axis  $\hat{A}$   $\hat{v}$  Velocity vector of the particle P is tangent to the path with magnitude  $v$   $dr/dt = v = ds/dt$   $(\hat{r}, \hat{\theta}, \hat{\phi})$ ,  $\hat{r}, \hat{\theta}, \hat{\phi}$ ,  $\hat{r}, \hat{\theta}, \hat{\phi}$ ,  $\lim_{\Delta t \rightarrow 0} \sin \Delta \theta / \Delta t = \dot{\theta}$   $r, \dot{r}, \ddot{r}$   $t, dt, ds, v, s, BP, r, t$

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### **Vector Mechanics for Engineers: Statics by Ferdinand P. Beer**

Ferdinand P. Beer & E. Russell Johnston Jr. Vector Mechanics for Engineers ( Dynamics ) McGraw-Hill Book Company Inc. 1977 ( N.B.; book page numbering follows on from companion volume 'Statics' ) Acrobat 7 Pdf 127.0 Mb.

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Seventh Vector Mechanics for Engineers: Dynamics Edition 12 - 4 Dynamic Equilibrium Alternate expression of Newton's second law,  $m\mathbf{a} = \sum \mathbf{F}$  inertial vector  $\mathbf{F} = m\mathbf{a}$  With the inclusion of the inertial vector, the system of forces acting on the particle is equivalent to zero. The particle is in dynamic equilibrium.

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Vector Mechanics for Engineers: Statics dition 7- 22 Sample Problem 7.6  $\hat{c}$  The change in moment between A and B is equal to area under shear curve between the points. The parabolic shear curve results in a cubic moment curve.  $\hat{c}$  The change in moment between B and C is equal

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loose thinking with concrete and simple mechanics problem-solving skills that live harmoniously with a useful mechanical intuition. Knowledge of freshman calculus is assumed. Although most students have seen vector dot and cross products, vector topics are introduced from scratch in the context of mechanics.

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Vector Mechanics for Engineers: Dynamics dition Dynamic Equilibrium 12 - 8  $\hat{c}$  Alternate expression of Newton's second law,  $\mathbf{F} = m\mathbf{a}$  inertial vector  $\mathbf{F} = m\mathbf{a}$   $\hat{c}$  With the inclusion of the inertial vector, the system of forces acting on the particle is equivalent to zero. The particle is in dynamic equilibrium.  $\hat{c}$  Methods developed for ...

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