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In this paper the two Stanford courses of one quarter (10 weeks) each covering the material of "Digital Control of Dynamic Systems" by the authors (Franklin and Powell, 1980) are described.

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### Introduction to Digital Control of Dynamic Systems And

•!Simpliﬕed Dynamic Model –!Rotary inertia, J, is the sum of motor and load inertias –!Internal damping neglected –!Output speed, y(t), rad/s, is an integral of the control input, u(t) –!Motor control torque is proportional to u(t) –!Desired speed, y c(t), rad/s, is constant 11 1/J Model of Dynamics and Speed Control First-order ...

### **Dynamic Effects of Feedback Control - Princeton University**

introduction to digital control of mechanical systems with an emphasis on applications. The desire to write this book arose from my frustration with the existing texts on digital control, which|while they were exhaustive|were better suited to reference needs than for tutorial use.

#### **Introduction to Applied Digital Control**

3 Prepared by Ben M. Chen Textbook â€" Primary selection • GF Franklin, JD Powell and ML Workman, Digital Control of Dynamic Systems, 3rd Edition, Addison Wesley, 1998. Homework assignments • There will be 3 homework assignments for this second part.

#### Ben M. Chen Associate Professor Department of Electrical

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This well-respected, market-leading text discusses the use of digital computers in the real-time control of dynamic systems. The emphasis is on the design of digital controls that achieve good dynamic response and small errors while using signals that are sampled in time and quantized in amplitude.

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